

An Efficient Load Balance Routing for Wireless Sensor Network

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Abstract--- Redundancy Management of heterogeneous wireless sensor networks, utilizing multipath routing to answer user queries in the presence of unreliable and malicious nodes. The concept of redundancy management is to exploit the tradeoff between energy consumption vs. the gain in reliability, timeliness, and security to maximize the system useful lifetime. Formulate an optimization problem for dynamically determining the best redundancy level to apply multipath routing for intrusion tolerance. A voting-based distributed intrusion detection algorithm is applied to detect and evict malicious nodes. Develop a novel probability model to analyze the best redundancy level in terms of path redundancy and source redundancy, as well as the best intrusion detection settings in terms of the number of voter sand the intrusion invocation interval under which the lifetime of network is maximized. The coverage time for a clustered wireless sensor network by optimal balancing of power consumption among cluster heads. Clustering significantly reduces the energy consumption of individual sensors, but it also increases the communication burden on CHs. Two mechanisms are proposed for achieving balanced power consumption in the stochastic case: a routing-aware optimal cluster planning and a clustering-aware optimal random relay. A sleeping node mechanism is used in order to gain maximum energy.

Keyword: - Heterogeneous wireless sensor networks, multipath routing, intrusion detection, reliability, security, energy conservation.

I. INTRODUCTION

A wireless sensor network (shortly WSN) consists of spatially distributed autonomous sensors to cooperatively monitor physical or environmental conditions, such as temperature, sound, vibration, pressure, motion or pollutants. The development of wireless sensor networks was motivated by military applications such as battlefield surveillance. They are now used in many industrial and civilian application areas, including industrial process monitoring and control, machine health monitoring, environment and habitat monitoring, healthcare applications, home automation, and traffic control. In addition to one or more sensors, each node in a sensor network is typically equipped with a radio transceiver or other wireless communications device, a small microcontroller, and an energy source, usually a battery.

A sensor node might vary in size from that of a shoebox down to the size of a grain of dust, although functioning "motest" of genuine microscopic dimensions have yet to be created. The cost of sensor nodes is similarly variable, ranging from hundreds of dollars to a few pennies, depending on the size of the sensor network and the complexity required of individual sensor nodes. Size and cost constraints on sensor nodes result in corresponding constraints on resources such as energy, memory, computational speed and bandwidth.

The multipath routing for intrusion tolerance query response success probability is maximized while prolonging the useful lifetime.

A unifying metric that considers the above two design tradeoffs, define the total number of queries the system can answer correctly until it fails as the lifetime or the mean time to failure (shortly MTTF) of the system, which can be translated into the actual system lifetime span given the query arrival rate. Aim is to find both the optimal redundancy levels and IDS settings under which the MTTF is maximized, when a given set of parameters characterizing the operational and environment conditions. The coverage time for a clustered wireless sensor network by optimal balancing of power consumption among cluster heads (shortly CHs). Clustering significantly reduces the energy consumption of individual sensors, but it also increases the communication burden on CHs.

To investigate this tradeoff, an analytical model incorporates both intra-and inters cluster traffic.

Depending on whether location information is available or not, considers optimization formulations under both deterministic and stochastic setups, using a Rayleigh fading model for inter cluster communications. Each CH routes its traffic directly to the sink or relays it through other CHs.

II. RELATED WORK

Over the past few years, many protocols exploring the tradeoff between energy consumption and QoS gain particularly in reliability in HWSNs have been proposed. In the optimal communication range and communication mode were derived to maximize the HWSN lifetime. In the authors devised intra-cluster scheduling and inter-cluster multi-hop routing schemes to maximize the network lifetime. They considered a hierarchal HWSN with CH nodes having larger energy and processing capabilities than normal SNs. The solution is formulated as an optimization problem to balance energy consumption across all nodes with their roles:

1. In either work cited above, no consideration was given to the existence of malicious nodes. In the authors considered a two-tier HWSN with the objective of maximizing network lifetime while fulfilling power management and coverage objectives. They determined the optimal density ratio of the two tier's nodes to maximize the system lifetime. Relative to our work also considers heterogeneous nodes with different densities and capabilities. However, our work considers the presence of malicious nodes and explores the tradeoff between energy consumption vs. QoS gain in both security and reliability to maximize the system lifetime. In the context of secure multipath routing for intrusion tolerance, provides an excellent survey in this topic.
2. In the authors considered a multipath routing protocol to tolerate black hole and selective forwarding attacks.

The basic idea is to use overhearing to avoid sending packets to malicious nodes. Our work also uses multipath routing to tolerate intrusion. However, we specifically consider energy being consumed for intrusion detection, and both CHs and SNs can be compromised for lifetime maximization. In a randomized dispersive multipath routing protocol is proposed to avoid black holes. The randomized multipath routes are dispersive to avoid the black hole and to enhance the probability of at least k out of n shares based on coding theory can reach the receiver.

3. The approach, however, does not consider intrusion detection to detect compromised nodes. Relative to our work also uses multipath routing to circumvent black hole attacks for intrusion tolerance. Moreover, we consider intrusion detection to detect and evict compromised nodes as well as the best rate to invoke intrusion detection to best tradeoff energy consumption vs. security and reliability gain to maximize the system lifetime.
4. In a decentralized rule based intrusion detection system is proposed by which monitor nodes are responsible for monitoring neighboring nodes. The monitor nodes apply predefined rules to collect messages and raise alarms if the number of failures exceeds a threshold value.
5. Our host IDS essentially follows this strategy, with the flaws of the host IDS characterized by a false positive probability (H_{pfp}) and a false negative probability (H_{pfn}). In however, no consideration is given about bad-mouthing attacks by compromised monitor nodes themselves, so if a monitor node is malicious, it can quickly infect others.
6. In a collaborative approach is proposed for intrusion detection where the decision is based on a majority voting of monitoring nodes. Their work, however, does not consider energy consumption issues associated with a distributed IDS, nor the issue of maximizing the WSN lifetime while satisfying QoS requirements in security, reliability and timeliness. Our voting based IDS approach extends with considerations given to the tradeoff between energy loss vs. security and reliability gain due to employment of the voting-based IDS with the goal to prolong the system lifetime.

III. INDICATION OF THE WSN

Wireless sensor network (shortly WSN) consists of spatially distributed autonomous sensors to cooperatively monitor physical or environmental conditions, such as temperature, sound, vibration, pressure, motion or pollutants. The development of wireless sensor networks was motivated by military applications such as battlefield surveillance. They are now used in many industrial and civilian application areas, including industrial process monitoring and control, machine health monitoring, environment and habitat monitoring, healthcare applications, home automation, and traffic control.

The cost of sensor nodes is similarly variable, ranging from hundreds of dollars to a few pennies, depending on the size of the sensor network and the complexity required of individual sensor nodes. Size and cost constraints on sensor nodes result in corresponding

constraints on resources such as energy, memory, computational speed and bandwidth. A sensor network normally constitutes a wireless ad-hoc network, meaning that each sensor supports a multi-hop routing algorithm.

A. Appearances of WSN

- Limited power they can harvest or store
- Ability to withstand harsh environmental conditions
- Ability to cope with node failures
- Mobility of node
- Dynamic network topology
- Communication failures
- Heterogeneity of nodes
- Large scale of deployment
- Unattended operation

Algorithms and protocols need to address the following issues

- Lifetime maximization
- Robustness and fault tolerance
- Self-configuration

B. Architecture of WSN

Wireless Sensor Network (shortly WSN) provides a low-cost and multifunctional means to link communications and computer networks to the physical world. It consists of base stations and a number of wireless sensors. Each sensor is a unit with wireless networking capability that can collect and process data independently. Sensors are used to monitor activities of objects in a specific field and transmit the information to the following base station:

1) Sensor node

This is a mobile node moving freely to monitors the physical environment. Once it detects its physical target, it generates a data packet and sends it to the sink node via the wireless channel. The processor in the sensor node may be set the threshold value to compare with the detected data before it generates and sends a data packet.

2) Sink node

This node collects all data packets from sensor nodes and uses them to analyze their targets.

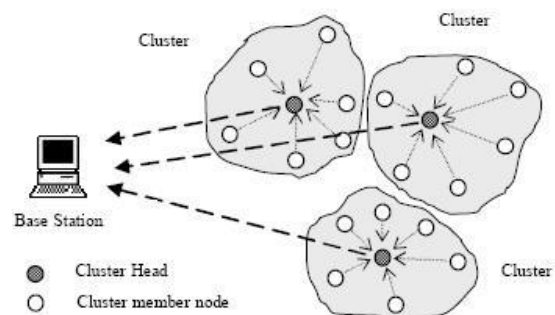


Fig. 1: Architecture of WSN.

3) Node Structure

A sensor node can be divided into four basic modules: transducer, processor, communications and power. The transducer module contains the physical sensing device and an analog-to-digital converter (ADC).

The communication module consists of a short-range radio transceiver. The power module is used to house the battery and provides energy to the other modules.

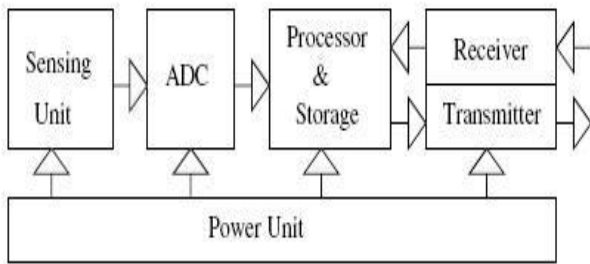


Fig. 2: Node Structure

4) Energy Constraints

The design of each system component can be optimized to minimize energy consumption. Energy consumption occurs in three aspects: sensing, communication, and data processing. Algorithmic modifications can often result in significant energy savings. Usually the communication of data consumes much more energy than sensing and data processing.

Energy is the scarcest resource of WSN nodes, and it determines the lifetime of WSNs. WSNs is meant to be deployed in large numbers in various environments, including remote and-hostile regions, with ad-hoc communications as key.

Therefore the algorithms and protocols are designed with the following features

- Lifetime maximization
- Robustness and fault tolerant
- Self-configuration

IV. SYSTEM MODEL

A HWSN comprises sensors of different capabilities. We consider two types of sensors: CHs and SNs. CHs are superior to SNs in energy and computational resources. We use ECH and ESN init to denote the initial energy levels of CHs and SNs, respectively. While our approach can be applied to any shape of the operational area, for analytical tractability, we assume that the deployment area of the HWSN is of size A_2 . CHs and SNs are distributed in the operational area. To ensure coverage, we assume that CHs and SNs are deployed randomly and distributed according to homogeneous spatial Poisson processes with intensities λ_{CH} and λ_{SN} , respectively, with $\lambda_{CH} < \lambda_{SN}$. The radio ranges used by CH and SN transmission is denoted by r_{CH} and

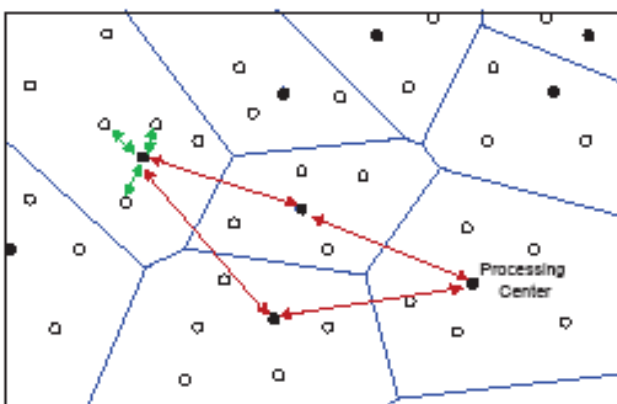


Fig. 3: System model

r_{SN} , respectively. The radio range and the transmission power of both CHs and SNs are dynamically adjusted throughout the system lifetime to maintain the connectivity

between CHs and between SNs. Any communication between two nodes with a distance greater than single hop radio range between them would require multi hop routing. Due to limited energy, a packet is sent hop by hop without using acknowledgment or retransmission.

Cluster head

Q Cluster Node

V. DYNAMIC AND AUTONOMOUS NETWORK OPERATION

Sensors are often deployed and arranged in environments that are inaccessible to humans (e.g., dropped from an airplane into remote mountainous regions). The topology of a WSN changes frequently due to failures of the sensor nodes. Therefore, protocols and algorithms with self-organizing ability are preferred.

The major performance evaluation metrics of MAC protocols are

1. Power conservation.
2. Average end-to-end delay.
3. Throughput.
4. Control overhead.

It is rather critical to operate a WSN at extremely low power levels. Although many solutions are available for conventional wireless networks, they are becoming obsolete and do not cater to present day requirements. Cellular networks, mobile ad-hoc network (MANET), and short-range wireless local area networks, however are unsuitable for achieving the unique characteristics of a large-scale WSN.

A. MAC Layer and Architecture

IEEE 802.11 MAC layer protocol is the main area of study. Since IEEE 802.11 Distributed Foundation Wireless Media Access Control (DFWMAC) is the standard for wireless ad hoc and infrastructure LANs, and it is widely used in almost all of the test beds and simulations for wireless ad-hoc networks research.

The main job of the MAC protocol is to regulate the usage of the medium, and this is done through a channel access mechanism. A channel access mechanism is a way to divide the main resource between nodes, the radio channel, by regulating the use of it. It tells each node when it can transmit and when it is expected to receive data.

The channel access mechanism is the core of the MAC protocol. In this section, we describe TDMA, CSMA and polling which are the 3 main classes of channel access mechanisms for radio. The MAC functional description is presented in this clause. The architecture of the MAC sub-layer, including the distributed coordination function (DCF), the point coordination function (PCF), and their coexistence in an IEEE 802.11 LAN.

VI. DISTRIBUTED COORDINATION FUNCTION (SHORTLY DCF)

The fundamental access method of the IEEE 802.11 MAC is a DCF known as carrier sense multiple accesses with collision avoidance (CSMA/CA). The DCF shall be implemented in all STA, for use within both IBSS and infrastructure network configurations. For a STA to transmit, it shall sense the medium to determine if another STA is transmitting. If the medium is not determined to be busy the transmission may proceed.

The CSMA/CA distributed algorithm mandates that a gap of a minimum specified duration exist between contiguous frame sequences. A transmitting STA shall ensure that the medium is idle for this required duration before attempting to transmit. If the medium is determined to be busy, the STA shall defer until the end of the current transmission.

A. Point coordination function (shortly PCF)

The IEEE 802.11 MAC may also incorporate an optional access method called a PCF, which is only usable on infrastructure network configurations. This access method uses a point coordinator (shortly PC), which shall operate at the access point of the BSS, to determine which STA currently has the right to transmit. The operation is essentially that of polling, with the PC performing the role of the polling master.

The PCF shall distribute information within Beacon management frames to gain control of the medium by setting the network allocation vector (shortly NAV) in STA. The access priority provided by a PCF may be utilized to create a contention-free (shortly CF) access method

B. Routing Protocols in WSN

Routing protocols have been developed which support establishing and maintaining the multi hop routes in MANET. These algorithms can be classified in to two different categories on-demand (reactive) such as DSR, AODV, and TORA and table driven (proactive) such as destination Sequenced Distance Vector protocol (DSDV).

C. Ad-Hoc on-Demand Distance Vector (AODV)

AODV stands for Ad-Hoc On-Demand Distance Vector and is, as the name already says, a reactive protocol, even though it still uses characteristics of a proactive protocol. AODV takes the interesting parts of DSR and DSDV, in the sense that it uses the concept of route discovery and route maintenance of DSR and the concept of sequence numbers and sending of periodic hello messages from DSDV.

Routes in AODV discovered and established and maintained only when and as long as needed. To ensure loop freedom sequence numbers, which are created and updated by each node itself, are used. These allow also the nodes to select the most recent route to a given destination node. AODV takes advantage of route tables. In these it stores routing information as destination and next hop addresses as well as the sequence number of a destination. Next to that a node also keeps a list of the precursor nodes, which route through it, to make route maintenance easier after link breakage.

To prevent storing information and maintenance of routes that are not used anymore each route table entry has a lifetime. If during this time the route has not been used, the entry is discarded.

There are three phases

1. Route Discovery
2. Route Maintenance
3. Route Determination

D. Dynamic Source Routing (DSR)

The Dynamic Source Routing protocol (shortly DSR) is a simple and efficient routing protocol designed specifically for use in multi-hop wireless ad hoc networks of mobile nodes. DSR allows the network to be completely self-organizing and self-configuring, without the need for

any existing network infrastructure or administration. Dynamic Source Routing, DSR, is a reactive routing protocol that uses source routing to send packets.

DSR uses source routing, i.e. the source determines the complete sequence of hops that each packet should traverse. This requires that the sequence of hops is included in each packet's header. Since finding a route is generally a costly operation in terms of time, bandwidth and energy, this is a strong argument for using source routing. Another advantage of source routing is that it avoids the need for up-to-date routing information in the intermediate nodes through which the packets are forwarded since all necessary routing information is included in the packets.

D. Route Discovery

Route Discovery is used whenever a source node desires a route to a destination node. First, the source node looks up its route cache to determine if it already contains a route to the destination. If the source finds a valid route to the destination, it uses this route to send its data packets. If the node does not have a valid route to the destination, it initiates the route discovery process by broadcasting a route request message. The route request message contains the address of the source and the destination, and a unique identification number.

E. Route Maintenance

Route Maintenance is used to handle route breaks. When a node encounters a fatal transmission problem at its data link layer, it removes the route from its route cache and generates a route error message. If though an intermediate station loses connectivity with next hop it initiates an ROUTE_ERROR message and broadcasts to its precursor nodes and marks the entry of the destination in the route table as invalid, by setting the distance to infinity.

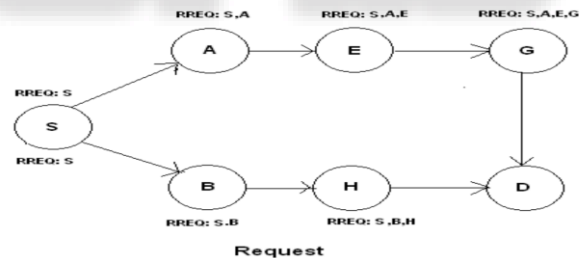


Fig. 4: Request phase in DSR

The route error message is sent to each node that has sent a packet routed over the broken link. When a node receives a route error message, it removes the hop in error from its route cache. Acknowledgment messages are used to verify the correct operation of the route links. In wireless

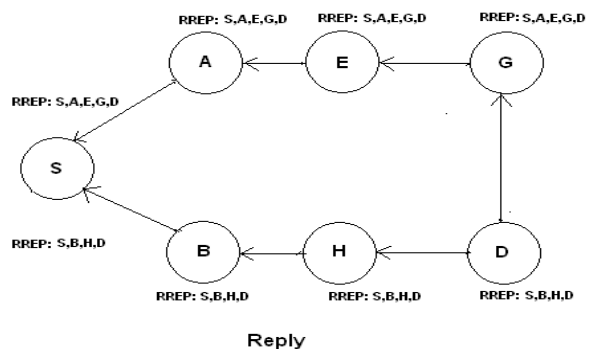


Fig. 5: Reply phase in DSR

networks acknowledgments are often provided as example. An existing standard part of the MAC protocol in use, such as IEEE 802.11.

VII. DESTINATION SEQUENCE DISTANCE VECTOR ROUTING (DSDV)

Destination Sequence Distance Vector (shortly DSDV) is a Proactive gateway discovery algorithm where the gateway periodically broadcasts a gateway advertisement message which is transmitted after expiration of the gateways timer. This protocol is based on classical Bellman-Ford routing algorithm designed for MANETS. Each node maintains a list of all destinations and number of hops to each destination. Each entry is marked with a sequence number. In DSDV, a sequence number is linked to a destination node, and usually is originated by that node (the owner). The only case that a non-owner node updates a sequence number of a route is when it detects a link break on that route. An owner node always uses even-numbers as sequence numbers, and a non-owner node always uses odd-numbers.

The list which is maintained is called routing table. The routing table contains the following

1. All available destinations' IP address
2. Next hop IP address
3. Number of hops to reach the destination
4. Sequence number assigned by the destination node
5. Install time

VIII. CONCLUSION & FUTURE WORK

An energy efficient cluster based load balance routing for wireless sensor networks utilizing multipath routing to answer user queries. a novel probability model to analyze the best redundancy level in terms of path redundancy (mp) and source redundancy (ms), as well as the best intrusion detection settings in terms of the number of voters (m) and the intrusion invocation interval (TIDS) under which the lifetime of a heterogeneous wireless sensor network is maximized while satisfying the reliability, timeliness and security requirements of query processing applications in the presence of unreliable wireless communication and malicious nodes. A routing-aware optimal cluster planning and a clustering-aware optimal random relays are used for efficient load balancing.

IX. FUTURE WORK

In the future, it will be necessary to have more studies on many types of algorithm that can work in many more application fields with more efficient energy use to look at infinite possibilities of sensor network used in numerous fields with numerous environment and application factors apply the best design parameter settings at runtime in response to environment changes to prolong the system lifetime.

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