

A Review on Image Demosaicing Methods

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Abstract— Digital Camera takes the images by employing a single image detector covering different color filter, so demosaicing is a process of converting these samples into a viewable format. Image Demosaicing is a method to build full resolution color image from Color Filter Arrays(CFA) images. In this paper, we've critically analyzed various demosaicing algorithms and basic demosaicing strategies and their common measures are also covered.

Keywords: Demosaicing, Color Filter Arrays

I. INTRODUCTION

Digital pictures or videos are presently a superior medium in atmosphere perception. they're these days nearly always captured directly by a digital (still) camera, instead of digitized from a video signal provided by associate degree analog camera as they accustomed be many years ago. Acquisition techniques of color pictures above all have concerned a lot of analysis work and undergone several changes. Despite major advancements, mass-market color cameras still typically use one detector and need resultant process to deliver color pictures. This procedure, named demosaicing, is that the key purpose of our study. The demosaicing issue is first conferred thoroughly.

There are two main styles of color digital cameras found on the market, counting on whether or not they plant 3 sensors or one. Single sensor cameras referred to as mono-CCD cameras, and equipped with spectrally-sensitive filters organized in step with a specific pattern. From such color filter arrays (CFA), associate intermediate gray-scale image is made, that then has got to be demosaiced into a real color image.

Digital space scan cameras square measure devices able to convert color stimuli from the determined scene into a color digital image (or image sequence) because of photosensors. Such Associate in Nursinging output image is spatially digitized, being fashioned of image parts (pixels). With every picture {element|component|constituent|element} is usually associated one photosensor element, that captures the incident intensity level of the colour stimulant.

The two main technology families obtainable for the look of camera photosensors area unit CCD (Charge-Coupled Device) and CMOS (Complementary Metal-Oxide Semiconductor) technologies, the previous being the foremost widespread one nowadays. The CCD technology uses the photoelectrical result of the semiconductor substrate, whereas CMOS is predicated on a photodetector and an energetic electronic equipment. each photosensors overall convert the intensity of the sunshine reaching every component into a proportional voltage. further circuits then converts this analog voltage signal into digital information. For illustration and explanation functions, the subsequent text relates to the CCD technology.

The various digital color cameras obtainable on the market may additionally be distinguished in keeping with whether or not they incorporate solely one device or three devices. It accordance with the colorful theory, 3-CCD

technology incorporates three CCD sensors, all being dedicated to a selected primary color. In most devices, the colour information from the determined scene is split onto the three sensors by means that of a trichroic prism assembly, made from two dichroic prisms. Alternately, the incident beam is also sent on three sensors, all being lined with a spectrally selective filter. The three part pictures IR, antibody and IB are at the same time noninheritable by the three CCD sensors, and their combination results in the ultimate color image. every digital three-CCD camera is characterised by its own spectral sensitivity functions $R(\lambda)$, $G(\lambda)$ Associate in Nursinging $B(\lambda)$ that take issue from the CIE color matching functions of the quality observer.

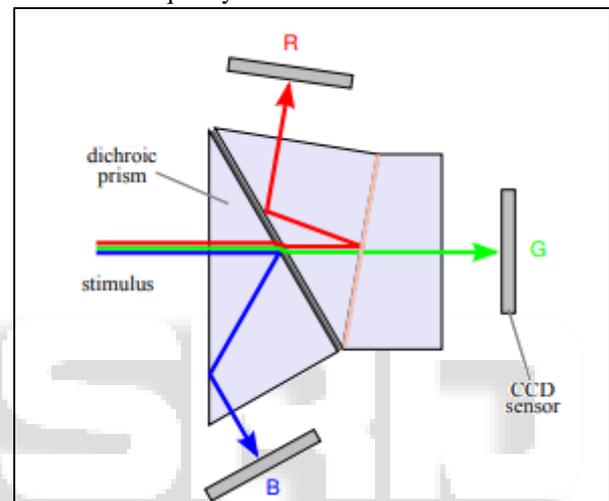


Fig. 1: Beam splitting by a trichroic prism assembly

Since 2005, Foveon Inc. has been developing the X3 device, that uses a multilayer CMOS technology. This new device relies on three superimposed layers of photosites embedded in a semiconductor substrate. It takes advantage of the actual fact that lights completely different of various wavelengths penetrate semiconductor to different as depicted in fig[3]. every layer thence captures one among the three primary colours, specifically blue, green and red, within the order in which light incident. All three photosites related to every component therefore offer signals from that the three part values area unit derived. Any camera equipped with this device is ready to create a real color image from three full part images, as do three-CCD-based cameras. This device has been initial used commercially in 2007 among the alphabetic character SD14 digital still camera. in line with its manufacturer, its spectral sensitivity higher fits with the CIE color matching functions than those of three-CCD cameras, providing pictures that area unit additional in keeping with human perception.

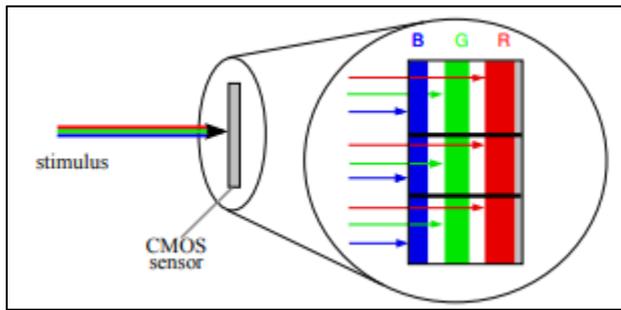


Fig. 2: Wavelength absorption within the Foveon X3 sensor

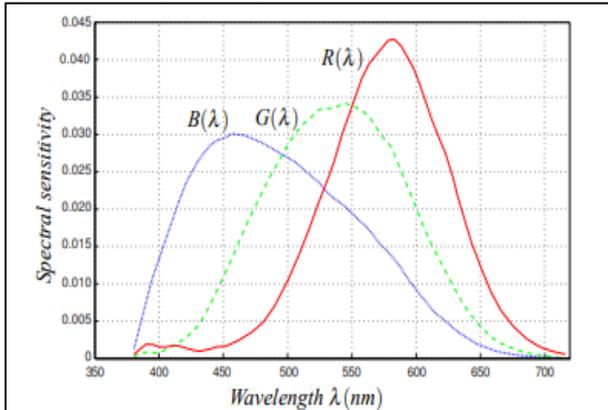


Fig. 3: Relative spectral sensitivity of the Foveon X3 sensor endowed with an infrared filter

Although three-CCD and Foveon technologies yield prime quality pictures, the producing prices of the device itself and of the device area unit high. As a consequence, cameras equipped with such sensors haven't been up to now cheap to everybody, nor widely distributed. so as to beat these value constraints, a technology employing a single device has been developed. the answer steered by Bayer from the Kodak company in 1976[2] remains the foremost wide utilized in industrial digital cameras these days. It uses a CCD or CMOS device lined by a filter (Color Filter Array, or CFA) designed as a mosaic of spectrally selective color filters, every of them being sensitive to a selected wavelength vary. At every component of the CCD device, only 1 out of the 3 color elements is sampled, Red (R), Green (G) or Blue (B). Consequently, only 1 color part is obtainable at every component of the image provided by the CCD charge transfer electronic equipment. This image if typically associated with because the raw image, however CFA image is most well-liked hereafter in our specific context. so as to get a color image from the latter, 2 missing levels should be calculable at every component due to a demosaicing scheme (sometimes spelled demosaicking).

As shown in fig 5, several different process tasks area unit classically achieved among a mono-CCD color camera (Lukac and Plataniotis, 2007). They consist as an example in raw device knowledge correction or, once demosaicing, in color improvement, image sharpening and noise reduction, thus on offer a “visually pleasing” color image to the user. These process tasks area unit essential to the standard of the provided image and, as a matter of reality, discriminate the assorted models of digital cameras, since makers and models of sensors don't seem to be thus various. The connected underlying algorithms have common options or basis, and parameter standardization is commonly a key

step resulting in additional or fewer residual errors. at the side of noise characteristics of the imaging device, such artifacts could incidentally be accustomed typify every camera model[3].

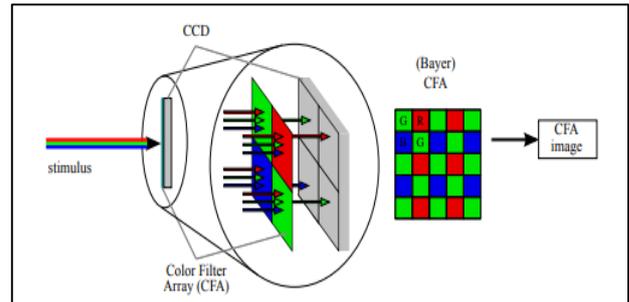


Fig. 4: Mono-CCD technology outline, using the Bayer Color Filter Array (CFA).

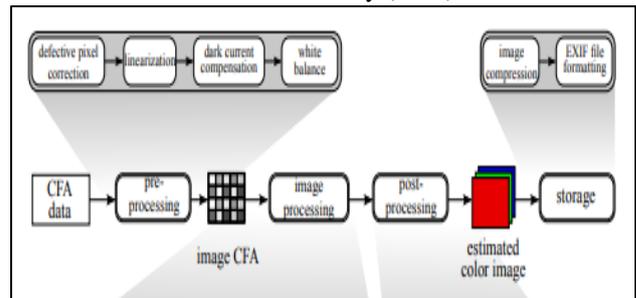


Fig. 5: Image acquisition within a mono-CCD color camera

Among several CFA patterns the painkiller pattern is one in every of the foremost popularly used color filter array pattern shown in figure a pair of which options blue and red filters at alternating constituent locations on rectangular grids within the horizontal and vertical directions and green filters area unit organized within the quincunx pattern at the remainder of the locations [2]. There area unit double as several green filters as red or blue ones. With this style pattern 0.5 (50%) of the image resolution is concentrated on predicting the green color band job to the human eye's larger sensitivity towards green lightweight as a result of the crest sensitivity of the Human sensory system lay in between the intermediate wavelength that justifies the additional green sampling lightweight as a result of the crest sensitivity of the Human sensory system lay in between the intermediate wavelength that justifies the additional green sampling A CFA usually has one color filter part for every sensing element then estimate the missing 2 color parts. This interpolation method is mostly referred to as ‘demosaicing’ as of the mosaic structure of the CFA pattern.

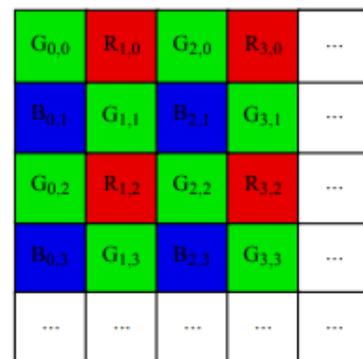


Fig. 5: Bayer Pattern CFA

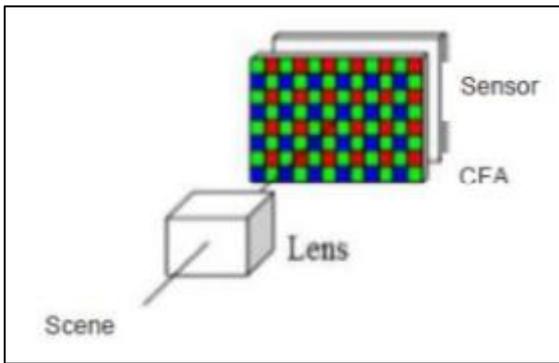


Fig. 6: Working of Single CCD Camera

Demosaicing is that the most important space of the image process utilized in digital cameras. The frustration of the used demosaicing method might weaken the full image quality considerably. That's why it's been taken as a vigorous analysis for many years. even if there has been recent tries to gift comprehensive demosaicing ways most demosaicing alternatives within the literature area unit made for the painkiller pattern. the foremost frequent approach for interpolation of missing pixels is by mistreatment the spacial invariant strategy like as an example additive or bicubic interpolation. however where there is a direct modification within the color modification that will cause the false color artifacts. the merchandise quality may be increased by creating the utilization of interpolation over color variations to create the foremost of affiliation between the colour channels. although the shortage of spacial adaptiveness would still certain the performance of interpolation. The potency of the interpolation technique depends upon the usage of each the spectral and spacial correlations.

Demosaicing Mathematical Representation: Estimated colours have less fidelity to colour stimuli from the determined scene than those provided by a three-CCD camera. rising the standard of color pictures nonheritable by mono-CCD cameras remains a extremely relevant topic, investigated by researchers and engineers[14].

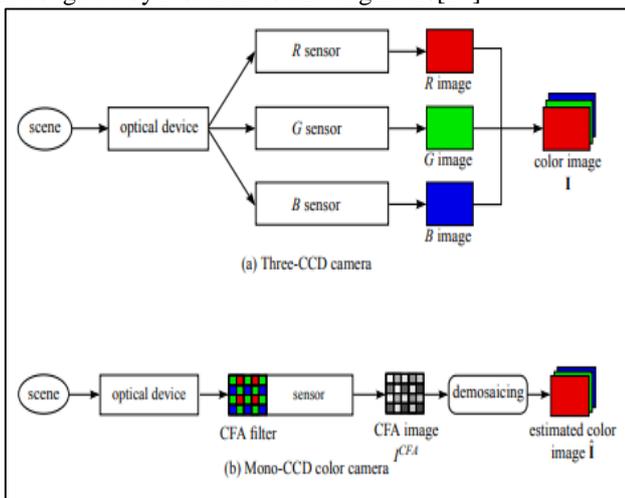


Fig. 7: Color image acquisition by different camera

Figure 7a outlines a three-CCD camera design, during which the colour image of a scene is created by combining the information from 3 sensors. The ensuing color image I is composed of 3 color part planes I_k, k ∈ {R, G, B}. In every plane I_k, a given constituent P is characterised by the amount

of the colour part k. A three-component vector outlined as I_{x,y}, (R_{x,y}, G_{x,y}, B_{x,y}) is so related to every constituent – settled at spatial coordinates (x,y) in image I. during a color mono-CCD camera, the colour image generation is kind of totally different, as shown in figure 8b : the only sensing element delivers a raw image, hereafter known as CFA image and denoted I^{CFA}. If the analgesic CFA is taken into account, to every constituent with coordinates (x,y) in image I^{CFA} is associated one color part R, G or B.

$$I_{x,y}^{CFA} = \begin{cases} R_{x,y} & \text{if } x \text{ is odd and } y \text{ is even} \\ B_{x,y} & \text{if } x \text{ is even and } y \text{ is odd,} \\ G_{x,y} & \text{otherwise.} \end{cases}$$

The color element levels vary from zero to 255 after they are quantal with eight bits. The demosaicing theme F, most frequently enforced as associate degree interpolation procedure, consists in estimating a color image I from I^{CFA}. At every picture element of the calculable image, the colour element obtainable in I^{CFA} at an equivalent picture element location is picked up, whereas the opposite 2 elements are calculable :

$$I_{x,y}^{CFA} \xrightarrow{F} I_{x,y} = \begin{cases} (R_{x,y}, \hat{B}_{x,y}, \hat{G}_{x,y}) & \text{if } x \text{ is odd and } y \text{ is even} \\ (\hat{R}_{x,y}, B_{x,y}, \hat{G}_{x,y}) & \text{if } x \text{ is even and } y \text{ is odd,} \\ (\hat{R}_{x,y}, \hat{B}_{x,y}, G_{x,y}) & \text{otherwise.} \end{cases}$$

Each triplet in equations (2) stands for a color, whose color element on the market at picture element P(x,y) in I^{CFA} is denoted R_{x,y}, G_{x,y} or B_{x,y}, and whose different 2 elements among R_{x,y}, G_{x,y} and B_{x,y} area unit calculable for I_{x,y}. Before we tend to get to the center of the matter, allow us to still precise many notations which will be most helpful later during this section. within the CFA image (see figure 9), four completely different structures area unit encountered for three[the three] × 3 spatial neighborhood, as shown on figure ten. for every of those structures, the picture element into account for demosaicing is that the central one, at that the 2 missing color elements ought to be calculable because of the on the market elements and their levels at the neighboring pixels. allow us to denote the aforesaid structures by the colour elements on the market on the center row, particularly , , and . Notice that and area unit structurally similar, aside from the slight distinction that elements R and B area unit changed. Therefore, they will be analyzed within the same approach, as will and structures. A generic notation is therefore utilized in the subsequent : the middle picture element is taken into account having (0,0) spatial coordinates, and its neighbors area unit remarked mistreatment their relative coordinates (δx,δy). Whenever this notation bears no ambiguity, (0,0) coordinates area unit omitted. Moreover, we tend to additionally typically use a letter (e.g. P) to generically see a picture element, its color elements being then denoted as R(P), G(P) and B(P). The notation P(δx,δy) permits to see a picture element because of its relative coordinates, its colours elements being then denoted Rδ x,δ y, Gδ x,δ y and Bδ x,δ y , as in figure ten.

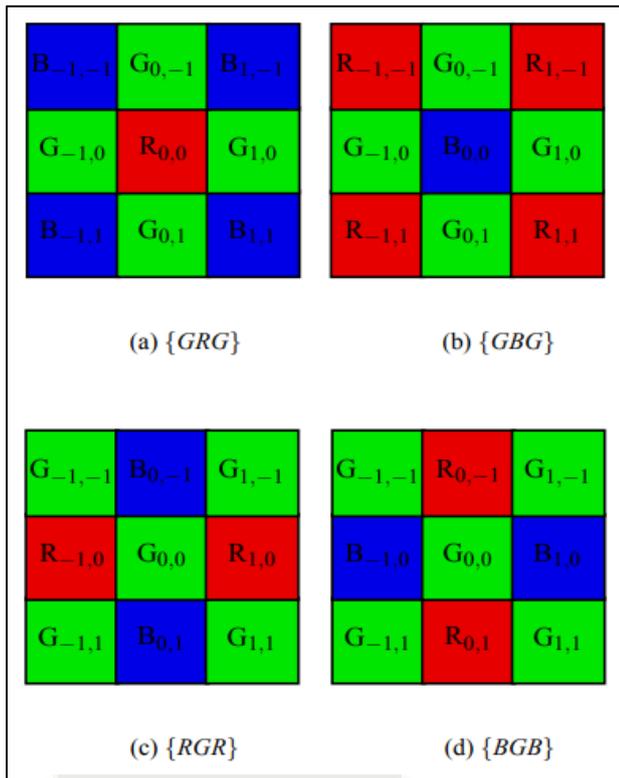


Fig. 8: 3x3 neighborhood structures of pixels in the CFA Common Demosaicing Artifacts

Because sampling a scene employing a CCD with a bayer pattern CFA measures just one third of the data of the first scene, many artifacts occur as a results of demosaicing. 2 of the foremost common area unit false coloring and zippering.

A. False Color Artifact:

A frequent and unfortunate artifact of CFA demosaicing is what's called false coloring. This artifact generally manifests itself on edges, wherever abrupt or unnatural shifts in color occur as a results of misinterpolating across, instead of on, an edge. Figure ten shows 3 pictures demosaiced with linear interpolation with samples of false colours. Image (a) has an alternating pattern of red and blue highlights moving on the left edge of the windscreen, alongside some red and blue highlights on brighter parts of the mirror. Image (b) shows another read of the truck's windscreen, wherever straight lines visible through the windscreen seem as alternating red and yellow pixels. Image (c) shows false coloring amidst high frequency info within the Ford logo's piece of writing.

Several strategies exist for preventing and removing this false coloring. sleek hue transition interpolation, that was reviewed in section a pair of, is employed throughout the demosaicing to stop false colours from manifesting themselves within the final image. However, alternative algorithms exist that may take away false colours once demosaicing. These have the good thing about removing false coloring artifacts from the image whereas employing a a lot of sturdy demosaicing algorithmic program for interpolating the red and blue color planes.

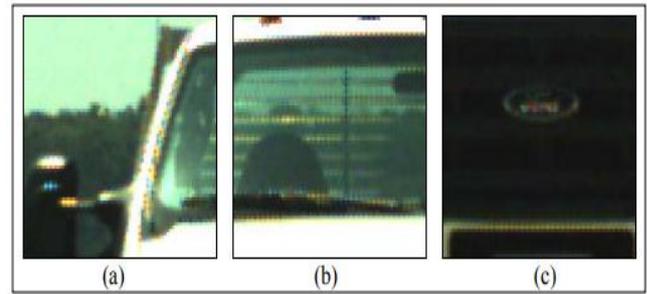


Fig. 9: Three images depicting the false color demosaicing artifact

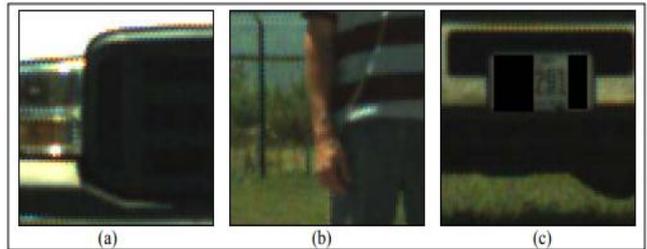


Fig. 10: Three images depicting the zippering artifact of CFA demosaicing

B. Zipper Artifact:

Another side effect of CFA demosaicing, that conjointly happens primarily on edges, is thought as the zipper impact. Simply put, zippering is Another name for edge blurring that happens in an on/off pattern on a footing. Figure 10 shows 3 pictures demosaiced with additive interpolation that includes the sting blurring zipper impact. Image (a) options a truck with zippering on the higher fringe of the grill and conjointly zippering on edges among the light source. Image (b) options an individual with zippering on the stripes in his shirt yet as zippering on the fence poles within the background of the image. Image (c) shows a vehicle plate with zippering on its six characters and a lot of zippering on the higher fringe of the bumper.

This impact happens once the demosaicing formula averages constituent values over the edge, particularly within the red and blue planes, leading to its characteristic blur. [the most impactful ways for preventing this effect is the varied algorithms that interpolate on, instead of across image edges. Pattern recognition interpolation, adaptive color plane interpolation, and directionally weighted interpolation all arrange to forestall zippering by interpolating on edges detected within the image.

II. LITERATURE SURVEY

Various papers have been presented on demosaicing, some of them are presented in this section.

In [4], Author planned a self-validation framework to resolve the colour demosaicking problem. Within the proposed selfvalidation framework, multiple algorithms under totally different hypotheses will be performed to come up with multiple candidates. Then the ultimate estimation of the missing color sample are going to be set by evaluating the native consistency of every algorithmic rule with double interpolation. With this framework, the strengths of various algorithms is combined and therefore eliminate color artifacts. The planned approach will create use of various

demosaicking algorithms and might benefit of them by evaluating their performances in every picture element employing a method known as double interpolation. within the proposed framework, the ultimate picture element price would be set by selecting among totally different candidates generated by all the input algorithms. Those pixels with highest native consistency would be chosen as final results. The experimental results show that the planned approach outperforms the opposite algorithms in each average objective quality assessment and subjective visual quality.

In [5], Author proposed a classified-based postcompensation algorithm for Color Filter Array (CFA) demosaicing. this system is used for improving the image quality of the interpolated results obtained by different CFA images. First, every pixel is classed according to its neighborhood texture variance and angle. Then, totally different Least-Mean-Square (LMS) filters are trained to adopt for dealing pixels of varied characteristics. As documented within the experimental results, the proposed scheme will considerably boost the image quality; additionally, a far better visual perceptual is obtained. The simulation results demonstrate that the proposed scheme will improve the image quality, particularly within the green plane, especially, those regions of upper dynamic ranges. Notably, the proposed technique is thought-about as effective postcompensation by applying for any former schemes to yield a good higher image quality.

In [6], Author presents a unique edge sensing-based demosaicing algorithmic rule for digital time delay and integration (DTDI) mosaic images, that are captured by DTDI linescan cameras and appropriate for industrial print inspection. They planned to use Sobel and interpolation-based masks to extract additional correct gradient data within the color difference domain. The extracted gradient data is used to help the design of the proposed demosaicing algorithmic rule. based on the extracted additional correct gradient data, the proposed edge sensing-based demosaicing algorithmic rule will generate good quality of a demosaiced image. The results demonstrate the potency of the planned demosaicing algorithmic rule in terms of demosaiced image quality.

In [7], Author proposed a demosaicing methodology that uses multi-scale color gradients to adaptively mix color difference estimates from totally different directions. The proposed solution doesn't need any thresholds since it doesn't make any exhausting choices, and it's non-iterative. though most fitted for the bayer CFA pattern, the strategy is extended to alternative mosaic patterns. The developed methodology is applied to bayer and Lukac patterns with nice results that shows that the link between gradients at totally different scales is very effective feature to optimally mix directional estimates. Experimental results show that it outperforms alternative accessible demosaicing strategies by a clear margin in terms of CPSNR and S-CIELAB measures for each mosaic patterns. the thought behind the projected methodology will prove to be helpful for image processing issues aside from CFA interpolation.

In [8], they suggested residual interpolation as an opportunity to the color distinction interpolation, wherein the residual is a difference among an determined and a tentatively estimated pixel value. They contain the proposed residual

interpolation into the gradient based totally threshold free (gbtf) set of rules, that's one of present day new demosaicking algorithms. experimental consequences exhibit that their proposed demosaicking algorithm using the residual interpolation can give Modern-day performance for the 30 pictures of kodak and imax datasets.

In [9], Author projected a changed gradient edge detection technique applied in demosaicing the colour filter array. Firstly, the adjacent pixels are ranged from high to small. Then, the absolute variations of sorted pixels are calculated to research the distribution of the possible edge. Finally the arithmetic operators being on the doable edge which being across the possible edge are designed to estimate the correct edge data. projected technique gets additional PSNR values than different strategies, even once the testing pictures have advanced edges. because of the analysis of the worth distribution of the adjacent pixels, the projected technique offers higher performance compared with the normal gradient edge detection strategies, that solely use the relative distinction to spot the sting data, and can't discover accurately the sting from completely different directions with shut gradient. the target experimental results indicate that the projected technique will get the upper PSNR values, even once it processes the images with complicated edges. The subjective comparison shows that the projected technique will improve visual quality than different strategies. It opens a chance of rising the accuracy of edge detection of the CFA image.

In [10], Author proposes a two-stage universal intra coding method for compression mosaic video sequences with arbitrary RGB-CFAs in high accurate video coding (HEVC). on the basis of the associated mosaic structure, the proposed method initially demosaics the neighbor reference pixels and so predicts the colour value of the target pixel using the color values of the identical color parts within the demosaiced reference pixels. Experimental results demonstrate that the proposed universal intra coding method achieves substantial improvement in each PSNR and bitrate whereas conserving the standard of the reconstructed video sequences in comparison with the present intra coding schemes. The proposed method avoids the problem in changing irregular CFA structure and therefore the quality degradation caused by color domain transformation. moreover, since the proposed intra coding method is meant specifically for the RGB-CFAs, it'd be attention-grabbing to extend the concept to tackle the non-RGB CFAs.

In [11] Author proposed a content adaptive demosaicing strategy utilizing structure analysis and correlation involving the red, green and blue planes. Those two aspects were chosen within the classification related to a block of pixels to created trained filters. The planned technique aims to reconstruct a primary good demosaiced image originating from a bayer pattern in any color filter array with efficiency. Experimental results showed that the proposed strategy performs relatively as higher end methods. In [12] Author introduced a brand new metric for approximating structural instability in bayer image data. we have a tendency to show that the metric are often used to establish and classify validity of color correlation in native image regions. The metric is employed to enhance interpolation performance of associate existing state-of-the-art

single pass linear demosaicing algorithmic rule, with just about no impact on process GPGPU complexness and performance. using four completely different image sets, the modification is shown to exceed the first technique in terms of visual quality, by having a mean increase in PSNR of 0.7 dB within the red, 1.5 dB within the green and 0.6 dB within the blue channel respectively. due to fewer high-frequency artifacts, the average output data size conjointly decreased.

In [13] Author introduced a unified object function to recover noisy bayer inputs. Image demosaicing and denoising are import steps of image signal process. successive executions of demosaicing and denoising have essential drawbacks that they degrade the results of every alternative. Joint demosaicing and denoising overcomes the difficulties by finding the two problems in one model. This paper introduces a unified object function with hidden priors and a variant of ADMM to recover a full-resolution color image with a noisy bayer input. Experimental results demonstrate that our methodology performs higher than state-of-the-art methods in each PSNR comparison and human vision. additionally, our methodology is much robust to variations of noise level.

III. DISCUSSION

It has been found that almost all of the present literature doesn't target at least one amongst the following things:

A. Sharpe Color Transition:

Almost all the methods we discussed exhibits unpleasant visual artifacts like sharp color transition.

B. Pixel Lost:

As a results of transform domain strategies certain pixels might drift during conversion either original to transform or transformed signal to original pixel values

C. Uneven Illuminate:

The matter of uneven illuminate has been ignored within the majority of existing methods on color filter array. Most of the ways depends upon certain predefined rules no focus on the objects or regions within the given image; therefore might imbalance the illuminate of the output image.

IV. CONCLUSION

This paper is expounded to most of the of digital color cameras, that are equipped with one sensing element. The surface of this sensor is covered by a color filter array that consists in a mosaic of spectrally selective filters, in order that every sensor element samples just one of the three color elements Red, green or Blue. we tend to concentrate on the bayer CFA that is the most generally used. To estimate the colour (R,G,B) of every component during a true color image, one should determine the values of the two missing color elements at every pixel within the CFA image. This method is usually named as CFA demosaicing, and its result as the demosaiced image.

The implementation of demosaicing schemes must respect real-time constraints. Indeed, the time needed for image demosaicing must be less than the image acquisition time. therefore speed improvement of the demosaicing theme

is much required. Zipper effect causes edge sub-detection, whereas a high density of pixels affected with false colours tends to cause over-detection of edge pixels. sharpe color transition also makes the visual defect on edges.

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