

# An Efficient Singular Value Decomposition Based Filtering for GIF Image Denoising with Ridge let Approach

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**Abstract**— In this paper, we consider an image decomposition Model that provides a novel framework for image denoising. Image Denoising has been one of most important area of image processing and very important step in image preprocessing for over several decades. Image denoising is the process by means of which unwanted visual elements in an image is removed to make the image clear as well as better for processing. Various image processing algorithms have been proposed and validated over the years. Experiments on a whole image database tested with several denoising methods show that this framework can provide better results than denoising the image directly, both in terms of Peak signal-to-noise ratio and Structural similarity index metrics.

**Key words:** Denoising, Decomposition, Index Metrics, Signal-to-Noise Ratio

## I. INTRODUCTION

Image denoising is one of the most studied problem in image processing. Many algorithms have been developed to tackle this issue, with various characteristics in terms of denoising efficiency, applicability to different types of images and noise models, and running time. We wanted to create an image denoising techniques for animated GIF images. An animated gif images constructed of subsequent image frames which are having slight displacement between them.in such way that overall gif image looks animated. They differ from any normal image in a sense that each frame is interdependent on other frame and frame can be constructed through a previous frame and overall motion factors. Among this large collection of available methods, we can single out the very classical ones i.e iterative decomposition , which has a low algorithmic complexity and can be applied quickly even on large 2D or 3D signals; total-variation (TV) based methods which are very efficient in removing noise while preserving sharp edges in GIF images. In this project, we propose a simple iterative algorithm, called SVD, for estimating the singular value decomposition (SVD) of a noisy incomplete given matrix. Where  $I_{vd} = \sum (SVD) n$ , where  $n$  is such that  $I_{VDn-1} = I_{VDn-2}$ .

The Singular Value Decomposition is an important tool for linear algebra and can be used to invert or approximate matrices. The Singular Value Decomposition relies on first order optimization over orthogonal manifolds and automatically estimates the rank of the Singular Value Decomposition.

## II. IMAGE DECOMPOSITION IN A MOVING FRAME

### A. The Gray-Level Case

Let  $I: \Omega \subset \mathbb{R}^2 \rightarrow \mathbb{R}$  be a gray-level image, and  $(x, y)$  be the standard coordinate system of  $\mathbb{R}^2$ . We denote by  $I_x$  resp.  $I_y$  the derivative of  $I$  with respect to  $x$  resp.  $y$ , and by  $\nabla I$  the gradient of  $I$ .

Our image decomposition model for  $I$  is a two-stages approach: first, we construct an orthonormal moving frame  $(Z_1, Z_2, N)$  of  $(\mathbb{R}^3, 2)$  over  $\Omega$  that encodes the local geometry of  $I$ . Then, we compute the components  $(J_1, J_2, J_3)$  of the  $\mathbb{R}^3$ -valued function  $(0, 0, I)$  in that moving frame. More precisely, we consider a scaled version  $\mu I$  of  $I$ , for  $\mu \in [0, 1]$ , and its graph, which is the surface  $S$  in  $\mathbb{R}^3$  parametrized by

$$\psi : (x, y) \rightarrow (x, y, \mu I(x, y))$$



Fig. 1: From Left to Right: Gray-Level Image “Lena



Fig. 2: Original GIF Image



Fig. 3: Noise added in Successive Frame 1

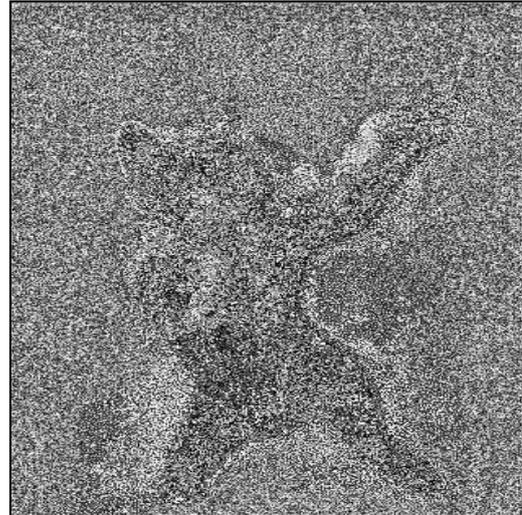


Fig. 5: Noise added in Successive Frame 3

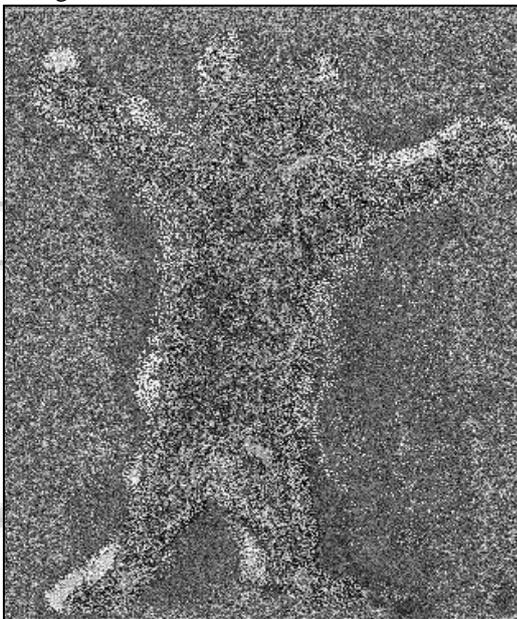


Fig. 4: Noise added in Successive Frame 2



Fig. 6: Noise added in Successive Frame 4

Approach/Noise Variance	5	10	15	20	25
PSNR Standard	56.23	54.34	52.60	51.23	50.24
PSNRMoving Frame	56.25	54.46	50.74	51.89	50.28

Table I

Approach/Noise Variance	5	10	15	20	25
SSIM Index Standard	95.23	91.34	87.60	84.23	81.24
PSNR Moving Frame	95.25	91.46	87.74	84.89	81.28

Table 2:

Parameter/Noise Variance	5	10	15	20	25
$\epsilon_3$	4.9	9.7	14.4	19.1	23.9

Table 3:

### III. METHODOLOGY

The rank estimation is based on the ratio between estimated large singular values and the sum of all singular values. We empirically evaluate the Singular Value Decomposition on synthetic matrices and image reconstruction tasks. The evaluation shows that the Singular Value Decomposition is comparable to the recently introduced methods for matrix completion such as singular value thresholding (SVT) and fixed-point iteration with approximate Singular Value Decomposition. The Singular Value Decomposition is a method for writing an arbitrary non square matrix as the product of two orthogonal matrices and a diagonal matrix. This technique is an important component of methods for approximating near singular matrices and computing pseudo-inverses. Several efficient techniques exist for finding the Singular Value Decomposition of a known matrix.

The behavior and performance of denoising algorithms are governed by one or several parameters, whose optimal settings depend on the content of the processed image and the characteristics of the noise, and are generally designed to minimize the mean squared error (MSE) between

the denoised image returned by the algorithm and a virtual ground truth. In this paper, we introduce a new Poisson–Gaussian unbiased risk estimator (PG-URE) of the MSE applicable to a mixed Poisson–Gaussian noise model that unifies the widely used Gaussian and Poisson noise models in fluorescence bioimaging applications. We propose a stochastic methodology to evaluate this estimator in the case when little is known about the internal machinery of the considered denoising algorithm, and we analyze both theoretically and empirically the characteristic of the PG-URE estimator. Finally, we evaluate the PG-URE-driven parametrization for three standard denoising algorithms, with and without variance stabilizing transforms, and different characteristics of the Poisson–Gaussian noise mixture.

#### IV. RESULT

We have developed a framework that enables any denoising method to take more into account the local geometry of the image to be denoised by preserving the moving frame describing the graph of a scaled version of the image.

#### V. CONCLUSION

Proposed algorithm though is meant for moving frame images, it can be very well apply to individual images because once we defined any frame into sub sequent smaller levels and apply our proposed denoising techniques the image retains the properties of the denoising. Therefore proposed system can not only be used clearing and cleansing the video or animated frames, but it also can be used in the context of a single image.

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