

Reliability Constrained Unit Commitment with Improved V2G Penetration using Hybrid PSO GSA

S. Vignesh Raj¹ A. Azeezur Rahman²

¹PG Scholar ²Assistant Professor

^{1,2}Department of Applied Mechanics

^{1,2}Sri Muthukumaran Institute of Technology, Chennai

Abstract— Vehicle to grid is a new technology which is integrating huge amount of electric vehicles as modern energy storage into the electric utility grid. Plug in electric vehicles have bidirectional energy flow i.e. they can either inject power to grid or draw from it. Vehicles are charged at off peak time and they discharge their power at peak time which is acting as a spinning reserve. Thus it reduces the dependency on small expensive units, optimizing the fluctuation of the load curve and also reduces the emission. Reliability constrained unit commitment is applied to minimize the cost economically and schedule unit reserves like spinning reserves to provide system reliability. In this paper unit commitment is a master problem assigning on/off state of generating units and at the next step the sub problem solves the economic dispatch and finally the reliability issues. Reliability issues are considered as spinning reserves and the ability of the power system under study to supply loads. HPSOGSA is used to solve the unit commitment problem.

Key words: Electric Vehicles(EV), Vehicle to Grid(V2G), Reliability Constrained Unit Commitment, Hybrid Particle Swarm Optimization Gravitational search algorithm(HPSOGSA), Capacity outage Probability Table(COPT)

I. INTRODUCTION

Electrification has become a major trend for the future transportation, due to the increasing scarcity of energy sources and the growing environmental pollution. Currently, many governments and automobile manufactures focus on the research and promotion of electric vehicles (EVs). Although the deployment of EVs could reduce the dependence on fossil fuel and emissions of CO₂, a large number of EVs will significantly affect the operation and management of the power grid and this connection between the vehicle and the grid is known as vehicle to grid technology. Vehicle to grid is a new technology which is integrating huge amount of electric vehicles as modern energy storage into the electric utility grid. Plug in electric vehicles have bidirectional energy flow i.e. they can either inject power to grid or draw from it. Vehicles are charged at off peak time and they discharge their power at peak time which is acting as a spinning reserve. Thus they are acting as load leveling and peak shaving[1]. Then it reduces the dependency on small expensive units, optimizing the fluctuation of the load curve[5] and also reduces the emission[9].

Reliability constrained unit commitment is applied to minimize the cost economically and schedule unit reserves like spinning reserves to provide system reliability[4]. In this paper unit commitment is a master problem assigning on/off state of generating units and at the

next step the sub problem solves the economic dispatch and finally the reliability issues. Reliability issues are considered as spinning reserves and the ability of the power system under study to supply loads. The impact of EV on power system is demonstrated in many levels, such as generation, transmission and distribution. The impact of EVs on the unit dispatch is mainly reflected in two aspects: Firstly, the uncertainty of charging behavior will affect the load demand, and this affection will spread to the unit commitment results. Secondly, the vehicle to grid (V2G) technique makes it possible that EV can provide energy back to the grid, which can reduce the output of traditional units. The UC problem is a large-scale, non-linear, mixed integer combinatorial optimization problem with constraints. It is difficult to find the exact solution to the problem, so near-optimal solutions are preferred. Hybrid particle swarm optimization is the method to find the global optimal solution for this problem.

II. VEHICLE TO GRID TECHNOLOGY

In the block diagram the proposed framework of V2G. Generally, a multi-storey parking lot has about 300 parking places and the capacity of each GV is 5-20 kWh. Thus, the maximum energy capacity is up to 6 MWh when the parking lot is fully parked, which is remarkable to the power grid. Since only aggregated GVs can provide considerable energy to the power grid, the V2G framework is established based on the aggregation of GVs[10].

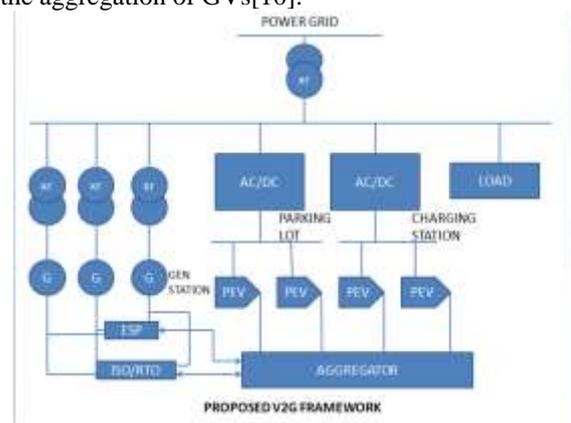


Fig. 1: Block Diagram of V2G.

When the aggregated GVs act as resources, a significant capacity produced by them can affect the grid operator such as the independent system operator (ISO) and regional transmission organization (RTO). The control signal from ISO/RTO which operates the bulk power system delivers the request of power to the aggregated GVs through the aggregator. When the aggregated GVs act as loads, they also send the request of charge to the energy service provider (ESP) through the aggregator.

The aggregator is responsible for collecting a certain number of GVs into a single entity and interacting with the power grid. It contacts with ISO/RTO and ESP directly instead of the aggregated GVs. Moreover, it manages the capacity and energy service collected by the aggregation of GVs, and dispatches the aggregated GVs either to sell their capacity and energy service to the grid or to be charged from the grid. The aggregator is the executor of the schedules derived from UC with GVs. It makes sure that a specified number of GVs will be connected to the power grid to provide power support.

The aggregator also has the function of determining which GVs should participate in the aggregation. In general, the participation depends on their state of charge (SOC), and the time and location that GVs can be connected to serve for the grid. Notice that the aggregation not necessarily consists of the GVs from the same parking lot or service.

III. RELIABILITY CONSTRAINED UNIT COMMITMENT

Reliability-constrained unit commitment (RCUC) is applied to minimize the costs economically, and schedules unit reserves like spinning reserves to provide system reliability; On the other hand, loss of load probability must be taken into consideration to obtain customers satisfactory of the power system.

Reliability constrained unit commitment consist of two parts.

- 1) Unit commitment and economic dispatch.
- 2) Reliability issues.

A. Unit Commitment and Economic Dispatch:

This chapter provides background of unit commitment (UC) and economic dispatch (ED), the impact of restructuring power industry on the development of the UC and ED. Unit commitment and economic dispatch have been used to plan over a given time horizon the most economical schedule of committing and dispatching generating units to meet forecasted demand levels and spinning reserve requirements while all generating unit constraints are satisfied. The generating unit schedule that yields minimum total production cost, which consists of cost of fuel, operating crew members, maintenance, starting up generating units and shutting down generating units, is the optimal solution of the UC and ED. With better computer hardware and programming software as well as better methodologies, the UC and ED have been enhanced in terms of speed and optimization. There are three main factors involving in obtaining an optimal generation planning or minimum total production cost. These factors are accurate forecasted demand, precise on-line and off-line schedule of generating units, and economic allocation of generation to available generating units, all of which are subject to demand and requirements, generating unit constraints.

B. Reliability Issues:

Reliability issues are considered as spinning reserves and the ability of the power system under study to supply loads. For reliability issues, two variables including spinning reserve and loss of load probability (LOLP) are obtained. COPTs are calculated based on the method where two reliability indices are considered. The LOLP and EUE

for a given solution of UC problem are calculated using the conventional "loss of load" method.

IV. LOAD LEVELING AND PEAK SHAVING

According to the concept of V2G, GVs can be charged from the power grid when power demand is low and discharged to supply the grid at peak hours instead of starting up some generating units..

During the off-peak conditions at night, GVs are considered as loads to be charged from the grid, hence leveling the low load. And during the peak conditions at daytime, GVs can deliver power to shave the peak load. Thus, the UC problem in a V2G system is to determine the start up and shut down schedules of generating units and GVs. The objective is not only to minimize the total operating cost, but also to minimize the total emissions at the same time.

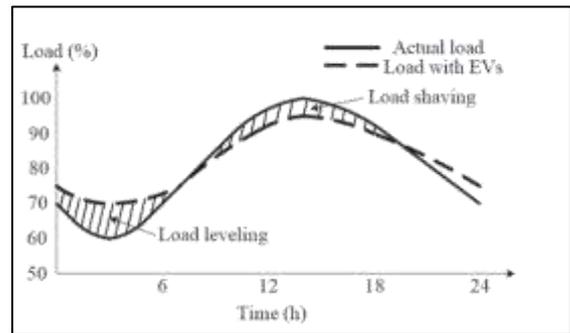


Fig. 2: Daily Load Curve

V. PROBLEM FORMULATION

A. Objective Function:

The basic goal in a UC problem is minimizing the total cost of the operating units while the hourly load demand and determined spinning reserve are met. The main frame of the problem formulation is the same as the conventional one where some new constraints and costs relevant to GVs of V2G are included in order to modify the whole problem as a UCV2G formulation.

1) Fuel Cost:

Fuel cost of a thermal unit is expressed as a second order function of each unit output as follows:

$$FC_i(P_i(t)) = a_i + b_i P_i(t) + c_i P_i^2(t) \quad (1)$$

where a_i , b_i , and c_i are positive fuel cost coefficients.

2) Start-up Cost:

The start-up cost for restarting a uncommitted thermal unit is included simply as follows

$$SC_i(t) = \begin{cases} h - cost_i & : MD_i \leq X_i^{off}(t) \leq H_i^{off} \\ c - cost_i & : X_i^{off}(t) > H_i^{off} \end{cases} \quad (2)$$

where:

$$H_i^{off} = MD_i + c - s - hour_i$$

The objective function for a cost-emission optimization of UC-V2G could be expressed as

$$\begin{aligned} \text{Min } \mathcal{J}C = & \text{fuel cost} + \text{start-up cost} + \text{V2G cost} \\ = & \sum_{i=1}^N \sum_{t=1}^H [(F C_i(P_i(t)) + S C_i(1 - I_i(t-1))) \\ & + \sum_{t=1}^H [CV N_{V2G}(t)]] \end{aligned} \quad (3)$$

B. Constraints:

Most of the constraints which must be satisfied in UC-V2G problem are the same as UC without V2G; these constraints are described briefly as follows:

1) *Power Balance Constraints:*

$$\sum_{i=1}^N I_i(t)P_i(t) + GEN_{V2G}(t) = D(t) + Losses \quad (4)$$

2) *Spinning Reserve Constraints:*

$$\sum_{i=1}^N I_i(t)P_i^{max}(t) + P_v^{max} N_{V2G}(t) \geq D(t) + R(t) \quad (5)$$

3) *Generation Constraint:*

$$P_i^{min} \leq P_i(t) \leq P_i^{max} \quad (6)$$

4) *Minimum Uptime/Minimum Downtime Constraint:*

$$\begin{cases} (1 - I_i(t+1))MU_i \leq X_i^{on}(t), & \text{if } I_i(t) = 1 \\ I_i(t+1)MD_i \leq X_i^{off}(t), & \text{if } I_i(t) = 0 \end{cases} \quad (7)$$

5) *Ramp Rate Constraint:*

$$P_i^{min}(t) \leq P_i(t) \leq P_i^{max}(t) \quad (8)$$

where $P_i^{min}(t) = \max(p_i(t-1) - RDR_i, P_i^{min})$ and $P_i^{max}(t) = \min(p_i(t-1) + RUR_i, P_i^{max})$.

6) *Gridable Vehicles Balance in UC with V2G:*

Different patterns could be taken into account based on the constraints contributed to the system and behavior of the vehicle users, two basic assumptions could be considered, a predefined number of vehicles are registered to charge from renewable sources and discharge to the grid during a 24 hours period. The next near practical assumption could be discussed as a flexible charging/discharging manner of vehicles during a predefined scheduling period. The constraint is formulated as follows:

$$\sum_{t=1}^H abs[N_{V2G}(t)] = Freq * N_{V2G}^{max} \quad (9)$$

7) *Charging/Discharging Frequency:*

In this study, a daily charging/discharging frequency is considered, however it should vary depending on the life time and the type of batteries.

8) *Required Time for Charging/Discharging:*

The required time for charging/discharging is directly depended on system characteristics. In this study the charging electric circuit with a rated power of 15 KW is considered.

9) *Availability of the Gridable Vehicles:*

All vehicles cannot charge/discharge at the same time. For reliable operation and control, certain number of vehicles

will charge/discharge at a time. A sensitivity analysis is also applied to observe the impact of V2G penetration level on reliability indices.

10) *Efficiency:*

Charging circuits and inverter efficiencies should be considered.

11) *State of Charge:*

Each vehicle has a desired departure state of charge level (SOC) which is determined by a uniformly distributed random number in the range of 30% to 60%.

C. Reliability Indices:

COPTs are calculated based on the method which is discussed in where two reliability indices are considered. The LOLP and EUE for a given solution of UC problem are calculated using the conventional "loss of load" method.

1) *Loss of Load Probability:*

The LOLP index expresses the probability that the generation system will not cover the forecasted demand.

$$LOLP_t = \sum_{j=1}^n PR_j LOSS_j, \quad t \in [1, T] \quad (10)$$

$$LOSS_j = \begin{cases} 1, & \text{if } CR_j < LOAD_t \\ 0, & \text{otherwise} \end{cases} \quad (11)$$

2) *Expected Unserved Energy:*

The EUE index expresses the expected energy that will not be served by generation system.

$$EUE_t = \sum_{j=1}^n PR_j LOSS_j (LOAD_t - CR_j), \quad t \in [1, T] \quad (12)$$

The incorporation of the above indices in the formulation of the UC problem is accomplished by implementing a maximum allowed limit for each index. In this paper the total EUE is considered as the reliability constraint as below:

$$EUE_{total} = \sum_{t=1}^T EUE_t \quad (13)$$

$$EUE_{total} \leq E_{max} \quad (14)$$

The proposed method is based on the implementation of an indirect penalty function. For each feasible solution provided by the HPSO algorithm, the corresponding EUE of the dispatch period is calculated. Then, the calculated EUE total is compared to a predefined maximum allowed limit (E_{max}), E_{max} is expressed as a percentage of the total energy demand. The determination of which is based on the desired level of reliability. The impact of the determined limit for EUE_{total} on the LOLP is then studied in each hour.

VI. HYBRID PARTICLE SWARM OPTIMIZATION AND GRAVITY SEARCH ALGORITHM:

In recent years, many heuristic evolutionary optimization algorithms have been developed. These include Particle Swarm Optimization (PSO), Genetic Algorithm (GA), Differential Evolution (DE), Ant Colony (AC), and Gravitational Search algorithm (GSA). The same goal for

them is to find the best outcome (global optimum) among all possible inputs. In order to do this, a heuristic algorithm should be equipped with two major characteristics to ensure finding global optimum. These two main characteristics are exploration and exploitation. Exploration is the ability of an algorithm to search whole parts of problem space whereas exploitation is the convergence ability to the best solution near a good solution. The ultimate goal of all heuristic optimization algorithms is to balance the ability of exploitation and exploration efficiently in order to find global optimum. According to exploration and exploitation in evolutionary computing are not clear due to lack of a generally accepted perception. In other hand, with strengthening one ability, the other will weaken and vice versa. Because of the above mentioned points, the existing heuristic optimization algorithms are capable of solving finite set of problems. It has been proved that there is no algorithm, which can perform general enough to solve all optimization problems. Merging the optimization algorithms is a way to balance the overall exploration and exploitation ability. PSO is one of the most widely used evolutionary algorithms in hybrid methods due to its simplicity, convergence speed, and ability of searching global optimum. There are some studies in the literature which have been done to synthesize PSO with other algorithms such as hybrid PSOGA, PODE, and PSOACO. These hybrid algorithms are aimed at reducing the probability of trapping in local optimum. Recently a novel heuristic optimization method is proposed called GSA. In this study, we present a new hybrid model combining PSO and GSA algorithms named PSO/GSA.

VII. SIMULATION RESULT

Simulations have been performed using Matlab. The three systems are taken.

- 1) System one has ten conventional generation units.
- 2) System two has ten conventional generators and a plug in vehicles which is acting as a spinning reserve.
- 3) System three has nine generation units and a plug in
- 4) Vehicles which is acting as a spinning reserve.

The fuel cost of the three systems are compared in the output graph shown below;

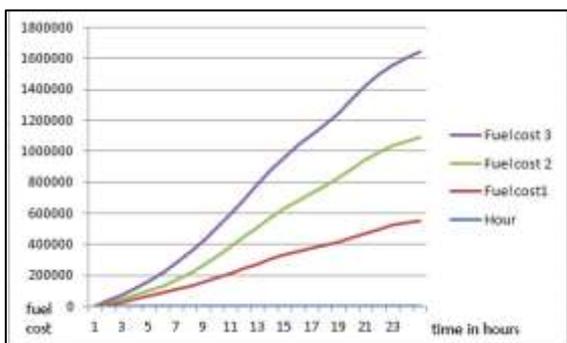


Fig. 3: Output Of Vehicle To Grid For A Day

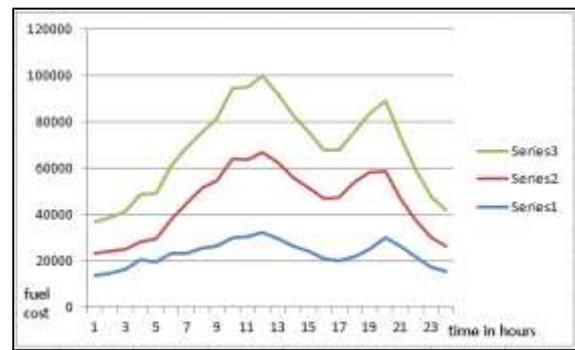


Fig. 5: Output Of Vehicle To Grid For Regular Hours.

Hence from the graph it is clear that on compared with the conventional generators the plug in vehicle reduces the total operating cost of the system by using hybrid particle swarm optimization.

VIII. CONCLUSION

High levels of V2G penetration in the power system without considering the reliability issues are not efficient and a tradeoff between the desired level of reliability and the total cost of the system should be taken into account. Thus the vehicles to grid technology reduces the total operating cost of the system. It also reduces the emission of green houses. It decreases the dependency on small expensive units and it is the promising modern energy storage for the future.

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